

An Introduction to De Rham Cohomology Groups

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Exterior Algebra

Tensors

Definition (Tensor)

A p -tensor on a vector space V is any real-valued function T such that on V^p that is multilinear i.e.

$$T(v_1, \dots, v_j + av'_j, \dots, v_p) = T(v_1, \dots, v_j, \dots, v_p) + aT(v_1, \dots, v'_j, \dots, v_p).$$

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Example

- A 1-tensor is a linear form so $\mathcal{J}^1(V^*) = V^*$. 1-tensor could be a measurement of the length of a vector.

Tensor Examples (contd.)

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Definition (Tensor Product)

If T is a p -tensor and S is a q -tensor, then $T \otimes S$ is a $p + q$ tensor:

$$T \otimes S(v_1, \dots, v_p, u_1, \dots, u_q) = T(v_1, \dots, v_p) \cdot S(u_1, \dots, u_q)$$

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Remark

Tensor product is not commutative!

Alternating Tensors

Definition (Alternating Tensor)

A p -tensor T is called *alternating* if $T = (-1)^\pi T^\pi$ where

$$T^\pi(v_1, v_2, \dots, v_p) = T(v_{\pi(1)}, v_{\pi(2)}, \dots, v_{\pi(p)})$$

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Let T be a p -tensor. We define the function $\text{Alt}(T)$ as

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Proposition

$\text{Alt}(T)$ is indeed an alternating tensor for all p -tensors T .

Alternating Tensors Examples

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- If T is a 1-tensor, every $\pi \in S_1$ is even so
$$T^\pi = T \implies T = (-1)^\pi T^\pi.$$

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When T is alternating and $T = (-1)^\pi T^\pi$,

$$\text{Alt}(T) = \frac{1}{p!} \sum_{\pi \in S_p} (-1)^\pi T^\pi = \frac{1}{p!} \sum_{\pi \in S_p} T = T.$$

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Remark

If $\Lambda^p(V^*)$ is set of alternating p -tensors, it's subspace of $\mathcal{J}^p(V^*)$.

Wedge Product

Definition (Wedge Product)

If $T \in \Lambda^p(V^*)$ and $S \in \Lambda^q(V^*)$, the *wedge product* is the $p + q$ tensor $T \wedge S \in \Lambda^{p+q}(V^*)$ defined by

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Proposition

If $\{\phi_1, \dots, \phi_k\}$ is a basis of V^* , then $\{\phi_I : 1 \leq i_1 < \dots < i_p \leq k\}$ is a basis of $\Lambda^p(V^*)$ where $I = (i_1, \dots, i_p)$ and $\phi_I = \phi_{i_1} \wedge \dots \wedge \phi_{i_p}$.

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Remark

The wedge product is anticommutative i.e.

$$T \wedge S = (-1)^{pq} S \wedge T$$

Exterior Calculus

Differential Forms

Definition (Differential p -forms)

Let X be a smooth manifold. A differential p -form on X is a function ω that assigns each point $x \in X$ to an alternating p -tensor ω_x on the tangent space of X at x . This means that $\omega_x \in \Lambda^p(T_x(X)^*)$. The set of all p -forms on X is denoted by $\Omega^p(X)$.

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Remark

- Recall tensors = measuring devices for vector space
- In a differential form, we assign each point on a smooth manifold to these measuring devices
- Differential form = instructions for how to measure tangent vectors at each point on a manifold

Differential Form Examples

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We can do operations on p -forms:

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- If $\phi : X \rightarrow \mathbb{R}$ is smooth, then $d\phi_x$ is 1-tensor on $T_x(X)$.

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- If $\phi : X \rightarrow \mathbb{R}$ is smooth, then $d\phi_x$ is 1-tensor on $T_x(X)$.
- $x \mapsto d\phi_x$ defines the 1-form, $d\phi$, on X called *differential* of ϕ .

The Exterior Derivative

Proposition

Let x_1, \dots, x_k be coordinate functions for \mathbb{R}^k and $dx_I = dx_{i_1} \wedge \dots \wedge dx_{i_p}$ where $I = (i_1, \dots, i_p)$. Every p -form on an open set $U \subseteq \mathbb{R}^k$ can be uniquely written as $\sum_I a_I dx_I$ where the sum ranges over all increasing index sequences I and the a_I are 0-forms on U .

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Definition (Exterior Derivative)

Let $\omega = \sum_I a_I dx_I$ be a smooth p -form on an open set of \mathbb{R}^k . The exterior derivative of ω is the $(p + 1)$ -form

$$d\omega = \sum_I da_I \wedge dx_I.$$

The Exterior Derivative Rules

Remark

Can define exterior derivatives on a smooth manifold X by considering coordinate charts.

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- Cocycle condition:

$$d(d\omega) = 0$$

The Pullback Map

Definition (Pullback Map)

If $f : X \rightarrow Y$ be a smooth map and let $df_x : T_x(X) \rightarrow T_{f(x)}(Y)$ be the derivative. The linear map $f^*\omega : \Omega^p(Y) \rightarrow \Omega^p(X)$ is called the *pullback by f at x* and maps a p -form on Y , ω , to a p -form on x , $f^*\omega$, defined by

$$(f^*\omega)_x(v_1, \dots, v_k) = \omega_{f(x)}(df_x(v_1), \dots, df_x(v_k)).$$

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$$(f^*\omega)_x(v_1, \dots, v_k) = \omega_{f(x)}(df_x(v_1), \dots, df_x(v_k)).$$

Proposition

The pullback commutes with the exterior derivative.

De Rham Cohomology Groups

Closed and Exact Forms

Definition

A p -form ω on X is *closed* if $d\omega = 0$ and *exact* if $\omega = d\theta$ for some $(p - 1)$ -form θ . The set of all closed p -forms on X is denoted by $Z^p(X)$ and the set of all exact p -forms on X is denoted by $B^p(X)$

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Definition

Two closed p -forms ω, ω' are called *cohomologous*, denoted by $\omega \sim \omega'$ if $\omega - \omega'$ is exact.

De Rham Cohomology Groups

Definition (De Rham Cohomology Groups)

Consider the following sequence

$$0 \rightarrow \Omega^0 \xrightarrow{d^0} \Omega^1 \xrightarrow{d^1} \Omega^2 \xrightarrow{d^2} \dots$$

which we call *cochain complex* where d^p is the exterior derivative on p -forms. The p th *De Rham cohomology group* (or p th *cohomology group* for short) is $H^p(X) = \ker(d^p) \setminus \text{im}(d^{p-1})$.

An element of $H^p(X)$ is called a *cohomology class* and the cohomology class containing the p -form ω is denoted by $[\omega]$ i.e.

$$[\omega] = \{\omega + d^{p-1}\omega' : \omega' \in \Omega^{p-1}\}.$$

Homotopy Invariance

The Theorem

Theorem (Homotopy Invariance)

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Definition

If $f : X \rightarrow Y$ is a smooth map, the pullback f^* creates the *induced cohomology map* (still denoted by f^*) from $H^p(Y)$ to $H^p(X)$:

$$f^*[\omega] = [f^*\omega].$$

The Proof

Remark

Homotopic smooth maps induce the same cohomology map.

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If $f, g : X \rightarrow Y$, what does it mean for $f^ = g^*$?*

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If $f, g : X \rightarrow Y$, what does it mean for $f^* = g^*$?

Answer

- If $f^* = g^*$, then

$$f^*\omega - g^*\omega = d\theta$$

since this would mean

$$f^*[\omega] - g^*[\omega] = [f^*\omega] - [g^*\omega] = [d\theta] = 0 \text{ or the identity.}$$

The Proof (contd.)

Answer (contd.)

- We can generate the θ with $h : \Omega^p(Y) \rightarrow \Omega^{p-1}(X)$ so condition becomes

$$f^*\omega - g^*\omega = d(h\omega) + h(d\omega).$$

The Proof (contd.)

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Definition

If X is a smooth manifold and $t \in I$, let $i_t : X \rightarrow X \times I$ be the map $i_t(x) = (x, t)$.

Lemma

For any smooth manifold X , there exists a homotopy operator between $i_0^, i_1^* : \Omega^p(X \times I) \rightarrow \Omega^p(X)$ for every p .*

The Proof (contd.)

Lemma

If X and Y are smooth manifolds and $f, g : X \rightarrow Y$ are homotopic smooth maps. For every p , the induced cohomology maps $f^, g^* : H^p(Y) \rightarrow H^p(X)$ are equal.*

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- Since f and g are homotopic smooth maps, they are smoothly homotopic so let $H : X \times I \rightarrow Y$ be the smooth homotopy.



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- $f = H \circ i_0$ and $g = H \circ i_1$



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- $f = H \circ i_0$ and $g = H \circ i_1$

$$f^* = (H \circ i_0)^* = i_0^* \circ H^* = i_1^* \circ H^* = (H \circ i_1)^* = g^*.$$



The Proof (contd.)

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$$(\tilde{f} \circ \tilde{g})^* = (\text{Id}_Y)^* \implies \tilde{g}^* \circ \tilde{f}^* = \text{Id}_{H^p(Y)}$$



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- Similarly, we have $\tilde{g} \circ \tilde{f} \simeq g \circ f \simeq \text{Id}_X$ so $\tilde{f}^* \circ \tilde{g}^* = \text{Id}_{H^p(X)}$.



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- By second lemma,

$$(\tilde{f} \circ \tilde{g})^* = (\text{Id}_Y)^* \implies \tilde{g}^* \circ \tilde{f}^* = \text{Id}_{H^p(Y)}$$

- Similarly, we have $\tilde{g} \circ \tilde{f} \simeq g \circ f \simeq \text{Id}_X$ so $\tilde{f}^* \circ \tilde{g}^* = \text{Id}_{H^p(X)}$.
- Therefore, the map $\tilde{f}^* : H^p(Y) \rightarrow H^p(X)$ is an isomorphism.



Applications

Corollary (Topological Invariance)

If X and Y are homeomorphic smooth manifolds, then their cohomology groups are isomorphic i.e. the cohomology groups are topologically invariant.

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Recall

The whole point of De Rham cohomology groups was to investigate when closed forms are exact.

Definition

A star-shaped set U is a set where there exists a $c \in U$ such that for every $x \in U$, the line segment between c and x is contained in U .

Poincaré Lemma

Theorem (Poincaré Lemma)

If U is a star-shaped open subset of \mathbb{R}^n , then $H^p(X) = 0$, or the trivial group, for $p \geq 1$.

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- Every point on X has neighborhood diffeomorphic to open ball in \mathbb{R}^n
- \mathbb{R}^n is star-shaped and cohomology groups are diffeomorphically invariant so we're done by Poincaré Lemma.



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- Let $\iota_x : \{x\} \rightarrow X$ be the inclusion map.
- $c_x \circ \iota_x = \text{Id}_{\{x\}}$ and $\iota_x \circ c_x \simeq \text{Id}_X$ so ι_x is homotopy equivalence
- By homotopy invariance, $H^p(X) = H^p(\{x\}) = 0$ since $\{x\}$ is a 0-manifold.



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- By previous lemma, we have $H^p(U) = 0$.



The End

Fin.